



## End Semester Examination – Nov/Dec – 2016

Code : **14EE2007**  
Sub. Name : **Induction and Synchronous Machines**

Semester : **2016-17 ODD**  
Duration : **3hrs**  
Max. marks : **100**

### ANSWER ALL QUESTIONS (5 x 20 = 100 Marks)

Q. No.	Sub Div.	Questions	Course Outcome	Marks														
1.	a.	Derive the torque equation and the maximum value of a three phase induction motor under running condition.	CO1	12														
	b.	Deduce the expression for ratio of full load torque and maximum torque.	CO1	04														
	c.	What are the effects of changes in supply voltage on torque and speed of a three phase induction motor?	CO1	04														
(OR)																		
2.	a.	A 440V, three phase, 50Hz, 37.3kW, star connected induction motor has the following parameters: $R_1 = 0.1\Omega$ , $X_1 = 0.4\Omega$ , $R_2 = 0.15\Omega$ , $X_2 = 0.44\Omega$ . Motor has stator core loss of 1250W and rotational loss of 1000W. It draws a no-load line current of 20A at a pf of 0.09 (lag). When motor operates at a slip of 3%, calculate (i) input line current and pf (ii) electromagnetic torque developed in Nm (iii) output and (iv) efficiency of the motor.	CO1, CO2	10														
	b.	Brief the methods of controlling the speed of a three phase slip ring induction motor from the rotor side.	CO1, CO2	10														
3.		Using double revolving field theory, explain why a single phase induction motor is not self starting. Draw the torque slip curve of a single phase induction motor.	CO1	20														
(OR)																		
4.	a.	Describe the constructional features and the operation of the following: (i) Stepper motor (ii) Shaded pole motor	CO1	10														
	b.	Write the different starting methods of a single phase induction motor?	CO1	10														
5.	a.	Derive the emf equation of an alternator.	CO2	6														
	b.	The following test results are obtained on a 6600V alternator: <table border="1"><tr><td><math>I_f</math> (amps)</td><td>16</td><td>20</td><td>25</td><td>37.5</td><td>50</td><td>70</td></tr><tr><td>EMF(volts)</td><td>3100</td><td>4200</td><td>4900</td><td>6600</td><td>7500</td><td>8300</td></tr></table> A field current of 20A is found necessary to circulate full load current on short circuit of the armature. Calculate the voltage regulation of the alternator by (i) ampere turn method (ii) Synchronous Impedance method.	$I_f$ (amps)	16	20	25	37.5	50	70	EMF(volts)	3100	4200	4900	6600	7500	8300	CO2	14
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6.		A 750-kVA, 11kV, 4pole, three phase star connected alternator has armature resistance and reactance of $1.6\Omega$ and $23.8\Omega$ respectively. Calculate the synchronizing power and torque per mechanical degree of displacement at (i) no load (ii) at full load 0.8 pf lagging. The terminal voltage in each case is 11kV.	CO2	20														
7.		A 5kVA, 415V, three phase, 4pole, star connected salient pole synchronous generator has direct axis reactance of $19\Omega$ and quadrature reactance of $15\Omega$ respectively. Determine the voltage regulation of the alternator operating at full load with 0.8 pf leading and lagging.	CO3	20														
(OR)																		

8.		Draw the phasor diagram of a Salient pole synchronous machine (both generator and motor) working at lagging and leading power factor conditions.	CO3	<b>20</b>
		<b><u>Compulsory:</u></b>		
9.	a.	Discuss briefly why synchronous motors are inherently not self starting. Explain the different methods for starting of synchronous motors.	CO1, CO3	<b>10</b>
	b.	Write a brief notes on effect of DC excitation on armature current and power factor of a synchronous motor.	CO3	<b>10</b>

ALL THE BEST